ProMinent®

Operating InstructionsDULCOMETER® D1C

Part 2: Adjustment and Operation, Measured Variable Standard Signal



D1C2-mA-001-D



Please completely read through operating instructions! · Do not discard! The warranty shall be invalidated by damage caused by operating errors!

1 Device Identification / Identity Code

_	DOL		ER® Con		eries	D1C	/ Vers	ion A					
			of moun										
	D		rol panel i	nstallati	on 96 x	x 96 r	nm						
L	W	Wall	mounting										
		0	Operati										
		1											
		2											
		3		00 V 50/60 Hz (only with panel installation)									
		4		100 V 50/60 Hz (only with panel installation) 24 V AC/DC									
		Ť		Measur	ed var	iable							
				Standar			20 m.	A					
									d variat	le			
				1 T	ermina	al, sta	ndard	signa	0/4-20	mA			
						Corre	ction	varial	ole				
					0 0	None							
							Fee	d forw	ard con	trol			
						0	Non						
					1	1				0/4-20	mA		
					1	2			cy 0-50				
					L	3	As f		cy 0-10				
							0	Noi	ntrol inp	out			
							1	Pau					
							ΗĖ	1 40		al outp	ut		
								0	Non				
								1			nal 0	/4-20	mA measured value
								2					mA control variable
								4	2 sta	andard s	ignal	0/4-2	0 mA output, free programmable
										Powe	er co	ntrol	
									Α	Alarm			
									G				t value relays
									M				enoid valve relays
									R	Alarm			servomotor with feedback
										0	No	mp co	ontroi
										2	_	ne o pum	ine
										1	1 00		ontrol characteristics
											0	_	one
											1	_	oportional control
											2		D control
											Т		Log output
													0 None
													Language
					1								D German
					1								E English
													F French
					1								I Italian N Dutch
					1								S Spanish
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					1								A Swedish
				B Portuguese									
					1								U Hungarian
			G Czech										
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2 Contents / General User Information

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General User Information

These operating instruction describe the technical data and function of the series DULCOMETER® D1C controller, provide detailed safety information and are divided into clear steps. The activities to be carried out are identified by bold bullets (•).



IMPORTANT:

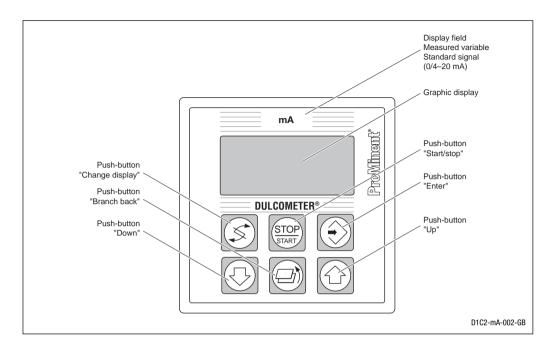
Please observe the parts of these operating instructions applicable to your particular version! This is indicated in the Section "Device Identification / Identity Code"!



IMPORTANT:

Correct measuring and dosing is only possible in the case of impeccable operation of the probe. The probe has to be calibrated / checked regularly!

3 Device Overview / Controls





CHANGE DISPLAY menu button

To change over within a menu level and to change from one variable to another within a menu point.



START/STOP menu button

Start/stop of control and metering function.



ENTER menu button

To accept, confirm or save a displayed value or status. For alarm acknowledgement.



UP menu button

To increase a displayed numerical value and to change variables (flashing display)



BRANCH BACK menu button

Back to permanent display or to start of relevant setting menu.



DOWN menu button

To decrease a displayed numerical value and to change variables (flashing display).

4 Functional Description

NOTE

Please refer to the description of the complete operating menu in Section 8 for a detailed description of the individual characteristics of the D1C controller!

4.1 Operating Menu

The D1C controller permits settings to be made in two different menus. All values are preset and can be changed in the complete operating menu.

The controller is delivered with a restricted operating menu so that the D1C controller can be used effectively in many applications from the very onset. If adaptations prove to be necessary, all relevant parameters can then be accessed by switching over to the complete operating menu.

4.2 Access Code

Access to the setting menu can be prevented by setting up an access code. The D1C controller is supplied with the access code 5000 which permits free access to the setting menu. The calibration menu remains freely accessible even when access to the setting menu is blocked by the code.

4.3 Control

The D1C can operate as a proportional controller or as a PID controller - dependent on the device version (see identity code) and the setting.

The controlled variable is recalculated every second. Control procedures which require rapid correction of setpoint deviations (less than approx. 30 seconds) cannot be processed with this controller. The cycle times must be taken into consideration when activating solenoid valves (pulse length) in the same way as their running times when activating servomotors (3-point).

Via the control input pause, the control function (selection of controlled variable) can be switched off. The calculation of the controlled variable starts again after cessation of "pause".

4.4 Feed Forward Control

The D1C controller can process a signal of a feed forward control. Depending on the device version (see identity code) and the setting, this signal can be obtained in any form of a 0–20 mA or 4–20 mA signal or as a digital contact signal with the maximum frequencies 10 Hz or 500 Hz.

During start-up, the zero point has to be checked. The multiplicative feed forward control is not designed for switching off permanently the actuating variable (signal \approx 0).

This signal can be used, for example, for flow-proportional metering (multiplicative effect) or feedforward-dependent basic load metering (additive effect). The result of control variable calculation from the proportional or PID control is multiplied by or added to the feedforward signal. A multiplicative feedforward variable at the level of the set rated value carries over the calculated control variable unchanged into the controlled variable:

Controlled variable = Feedforward variable/rated value x calculated control variable

An additive feedforward variable at the level of the rated value results in maximum controlled variable:

Controlled variable (max. 100 %) = Feedforward variable/rated value x max. controlled variable + calculated control variable

4.5 Error Messages

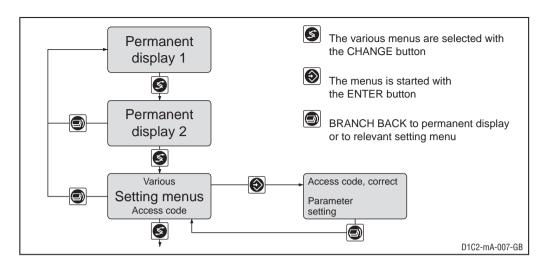
Error messages and information are indicated on the bottom line in the permanent display 1. Errors to be acknowledged (acknowledgement switches off the alarm relay) are indicated by the "E". Errors/notes which still apply after acknowledgement are indicated alternately. During correction variable processing (temperature for correction of pH-value), the value is indicated in the same line as the error/note. Faults which are rectified of their own accord due to changed operating situations are removed from the permanent display without the need for acknowledgement.

5 Display Symbols

The display of the D1C controller uses the following symbols:

Description	Comment	Symbol
Limit value transgression Relay 1, upper	Symbol left	1
Relais 1, lower	Symbol left	l l
Relais 2, upper	Symbol right	1
Relais 2, lower	Symbol right	ŀ
Metering pump 1 ↑ Control OFF	Symbol left	
Control ON	Symbol left	
Metering pump 2 ↓ Control OFF	Symbol right	
Control ON	Symbol right	
Solenoid valve 1 ♠ Control OFF	Symbol left	4
Control ON	Symbol left	
Solenoid valve 2 Control OFF	Symbol right	L
Control ON	Symbol right	<u> </u>
Servomotor Control, open relay		⊿
Control, close relay		△ k
Without control		4 k
Position feedback	The bar increases from left to right during opening	-
Stop button pressed		0
Manual metering		M
Fault		3

6 Operation



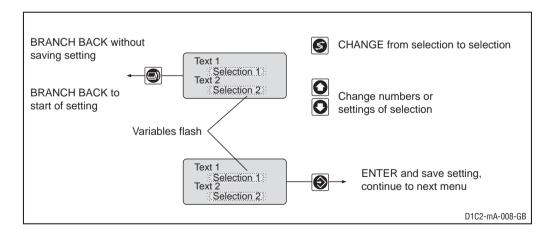
NOTE

Access to the setting menus can be barred with the access code!

The number and scope of setting menus is dependent on the device version!

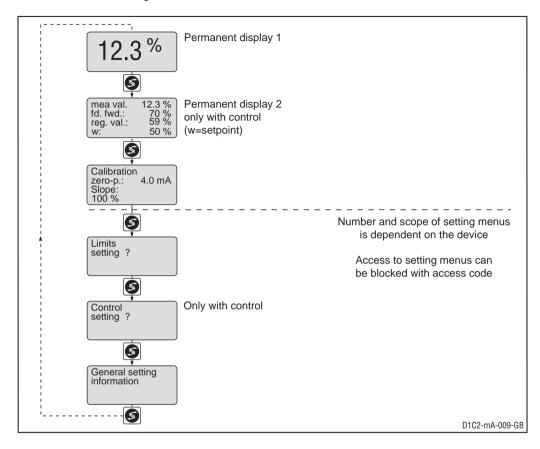
If the access code is selected correctly in a setting menu, then the following setting menus are also accessible!

If within a period of 10 minutes no button is pushed, the unit automatically branches back from the calibrating menu or a setting menu to the permanent display 1.

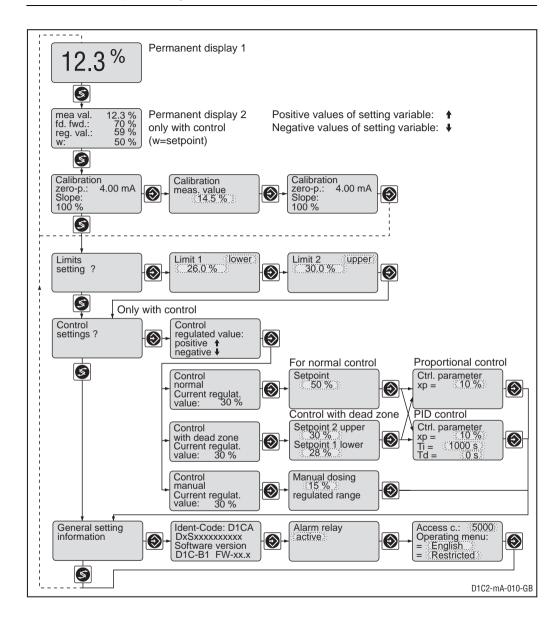


7 Restricted Operating Menu / Overview

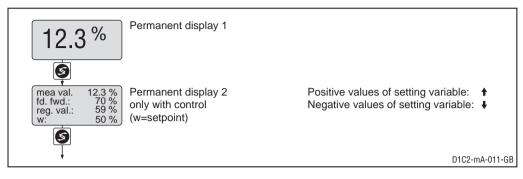
The restricted operating menu permits simple operation of the most important parameters. The following overview shows the settings which can be selected:



Restricted Operating Menu / Layout



Restricted Operating Menu / Description



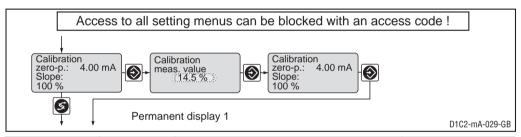
Calibration the Standard Signal (zero-point calibration):

During calibration, the control function persists. The standard signal of the output (measured value) remains unchanged. The measured value registered during the start of the calibration is proposed as value; this value is adjustable.



CAUTION:

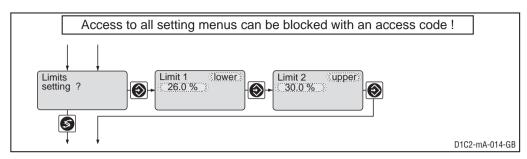
A change of the measuring unit (see page 15) must be done before calibration!



	Possible Values			
Initial value	Increment	Lower value	Upper value	Remarks
Measured value	0.1 %	-5 %	105 %	
	0.01 mA	−1.00 mA	21.00 mA	
	0.01 m	0 m	31.50 m	30.00 m
	0.1 %	0 %	105 %	100 %
	0.001 bar	0 bar	1.050 bar	1.000 bar
	0.001 bar	0 bar	5.250 bar	5.000 bar
	0.01 bar	0 bar	10.50 bar	10.00 bar
	0.1 bar	0 bar	105 bar	100.0 bar
	0.1 psi	0 psi	105 psi	100 psi
	1 psi	0 psi	1050 psi	1000 psi
	0.001 m ³ /h	0 m³/h	9.999 m³/h	9.999 m³/h
	0.1 m³/h	0 m³/h	105 m³/h	100 m³/h
	1 m³/h	0 m³/h	1050 m³/h	1000 m ³ /h
	0.1 gal/h	0 gal/h	105 gal/h	100 gal/h
	1 gal/h	0 gal/h	1050 gal/h	1000 gal/h
	1 ppm	0 ppm	1050 ppm	1000 ppm
	0.1 %RF	0 %RF	105 %RF	100 %RF
	0.01 mA	0/4 mA	21 mA	20 mA
	0.1 %	0 %	105 %	100 %

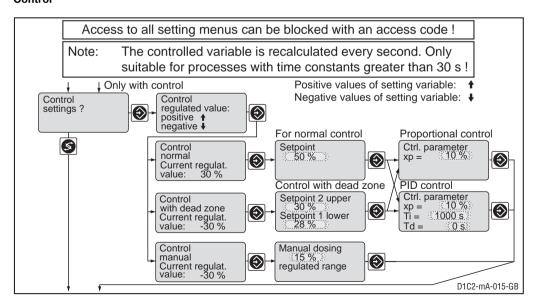
Restricted Operating Menu / Description

Limits



		Possible V	alues		
	Initial v	alue Increme	ent Lower value	Upper value	Remarks
3	it 1: lo	wer lower off *)	r		Limit transgression when exceeding or dropping below value *) only with limit value relay
Lim Lim	iit 2: 10 iit 1: 0.00	0.1 % 00 % 0.1 % 0 mA 0.01 m	-5 % -1.00 mA	105 % 105 % 21 mA 21 mA	measuring unit % measuring unit mA

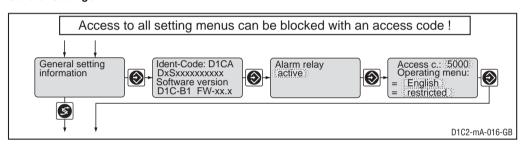
Control



Restricted Operating Menu / Description

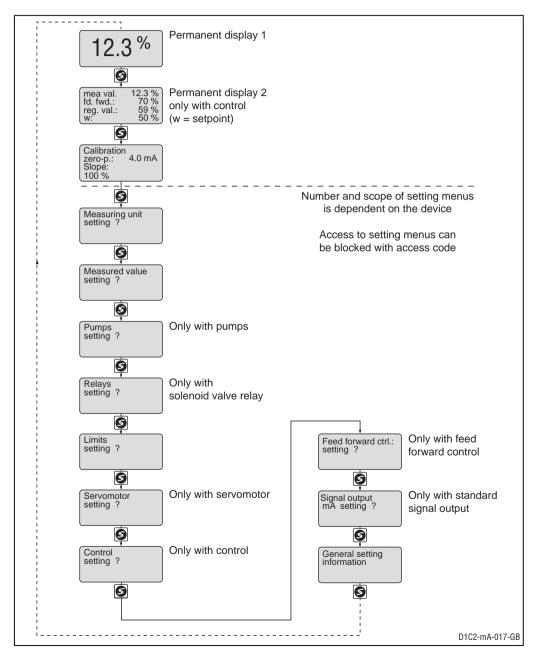
		Possible Values			
	Initial value	Increment	Lower value	Upper value	Remarks
Setpoint	50 % 10.00 mA	0.1 % 0.01 mA	−5.0 % −1.00 mA	105 % 21 mA	measuring unit: % measuring unit: mA 2 setpoints necessary for control with dead zone. Setpoint 1 > setpoint 2
					Adjustment of measuring on page 14
Control parameter xp	10 %	1 %	1 %	500 %	xp referred to measuring
Control parameter Tn	off	1 s	1 s	9999 s	range
Control parameter Tv	off	1 s	1 s	2500 s	Function off = 0 s
Manual metering	0 %	1 %	-100 %	+100 %	Function off = 0 s

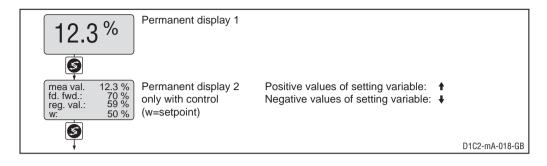
General Settings



		Possible Values			
	Initial value	Increment	Lower value	Upper value	Remarks
Alarm relay	active	active not active			
Access code	5000	1	1	9999	
Language	as per identity code	German English French Italian Spanish Dutch Polish Swedish Portuguese Czech Hungarian			
Operating menu	restricted	restricted complete			

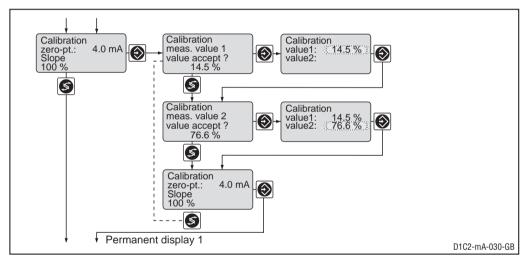
All parameters of the controller can be set in the complete operating menu. The following overview shows the settings which can be selected:





Calibration the Standard Signal (two-point calibration)

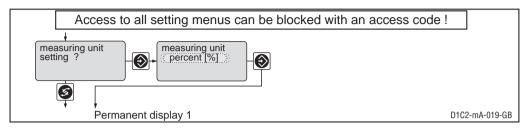
During calibration, metering is reduced to the set basic load. The standard signal of the output (measured value) is reduced to 0 mA or 4 mA. As value the measured value is proposed; this value is adjustable. (The slope is indicated as deviation measured slope to norm slope).



	Possible Values			
Initial value	Increment	Lower value	Upper value	Remarks
Measured value*	0.1 % 0.01 mA	−5 % −1.00 mA	105 % 21.00 mA	*for possible measuring values see page 10

Error message	Condition	Effect
Value distance too small	Δ value > 5.0 % Δ value > 1.00 mA	measured value deleted repeat calibration

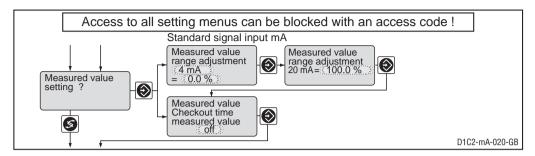
Measuring Unit



When changing the measuring unit the settings must be checked in all menues!

		Possible Values			
	Initial value	Increment	Lower value	Upper value	Remarks
Measuring variable	Measurement signal	Level Pressure Water flow rate Turbidity Humidity Measurement signal			
Measuring unit	0 - 100 %	0 - 30 m 0 - 100 % 0 - 1.000 bar 0 - 5.000 bar 0 - 10.00 bar 0 - 100.0 bar 0 - 100.0 psi 0 - 1000 psi			Level Pressure
		0 - 9.999 m³/h 0 - 100.0 m³/h 0 - 1000 m³/h 0 - 100.0 gal/h 0 - 1000 gal/h 0 - 1000 ppm			Water flow rate Turbidity
		0 - 1000 ppm 0 - 100.0 %RH 0/4 - 20 mA 0 - 100 %			Humidity Measurement signal

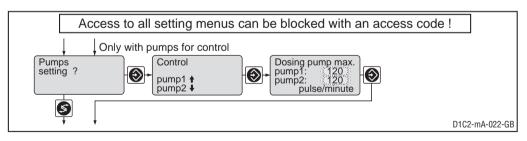
Measured value



When changing the range adjustment, the adjustments in all menus have to be checked!

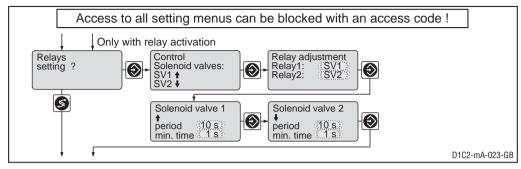
		Possible Values			
	Initial value	Increment	Lower value	Upper value	Remarks
Standard signal input lower signal limit	4 mA	0 mA 4 mA			
Allocated measuring range*	0–100.0 % 0–20.00 mA	0.1 % 0.01 mA	−5 % −1.00 mA	105 % 21.00 mA	Measurement signal *for other measuring ranges see page 10
Checkout time	off	1 s	1 s	9999 s	Constant measurement signal results in message and alarm. Function off = 0 s

Pumps



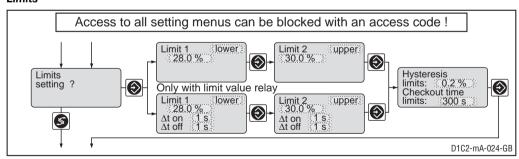
		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Max. stroke/minute of pumps 1 and 2	120	1	1	500	off = 0 strokes/min

Relay for solenoid valve activation



		Possible Values			
	Initial value	Increment	Lower value	Upper value	Remarks
Relay adjustment Relay 1	as per identity code	Solenoid valve 1 Limit value 1* Actuator 1 off			*When the setting is "Limit" the relays will not be disable during the pause or in case of a fault.
Relay 2		Solenoid valve 2 Limit value 2* Actuator 2 off			
Period	10 s	1 s	10 s	9999 s	
min. time	1 s	1 s	1 s	period/2	

Limits



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Type of limit trans- gression Limit 1: Limit 2:	lower upper	upper lower off *)			Limit transgression when exceeding or dropping below value *) only with limit value relay

			Possible values			
		Initial value	Increment	Lower value	Upper value	Remarks
Limit value	Limit 1: Limit 2:	0 % 100 %	0.1 % 0.1 %	–5 % –5 %	105 % 105 %	measuring unit percent
	Limit 1: Limit 2:	0 mA 20 mA	0.01 mA 0.01 mA	−1.00 mA −1.00 mA	21 mA 21 mA	measuring unit milliampere
Switch-on dela	ıy ∆t ON	0 s	1 s	0 s	9999 s	
Switch-off dela	ay ∆t OFF	0 s	1 s	0 s	9999 s	
Hysteresis limi	its	0.2 % 0.04 mA	0.1 % 0.01 mA	0.1 % 0.02 mA	105 % 21.00 mA	
Checkout time	limits	off	1 s	1 s	9999 s	Results in message and alarm. Off = 0 s: Function switched off, no message, no alarm

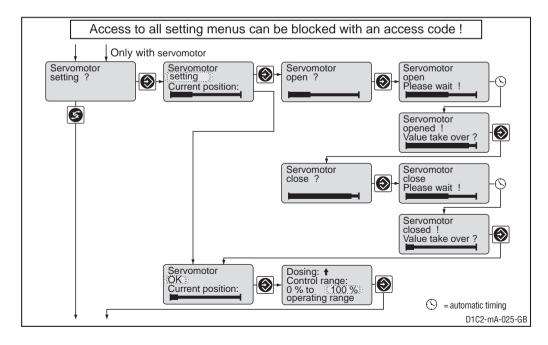
Servomotor

Activation of the servomotor must be carried out with the same meticulous care as taken when calibrating a measuring probe. The operating range is defined by the total resistance range of the feedback potentiometer. The maximum limit of the range actually used is set by defining the control range.



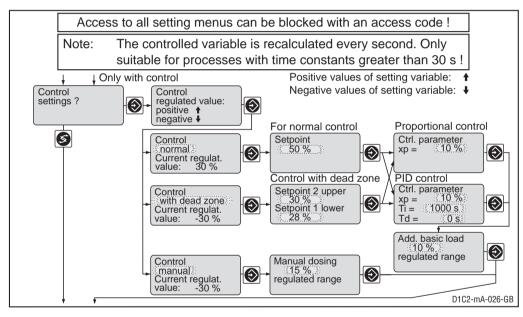
CAUTION:

To ensure correct operation, the activation time of the actuator used should not be less than 25 seconds for the control range from 0...100 %!



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Servomotor	Setting	Setting OK off			
Controll direction	↑	†			
Control range	100 %	1 %	10 %	100 %	in % of operating range

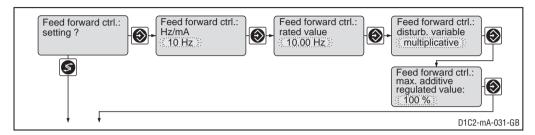
Control



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Control	normal	normal with dead zone manual			When controlling with dead zone, the feed forward control is not used for measured values within the dead zone.
Setpoint	1.0 ppm 10 %	0.01 ppm 0.1 %	–3 ppm –30 %	63 ppm 630 %	When measuring range concentration When measuring range saturation 2 setpoints necessary for control with dead zone. Setpoint 1 > setpoint 2

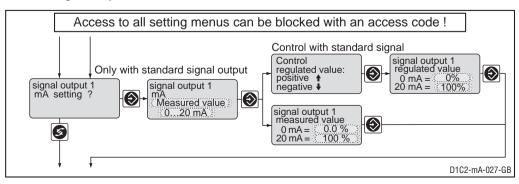
		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Control parameter xp Control parameter Tn Control parameter Tv Additional load Manual metering		1 % 1 s 1 s 1 % 1 %	1 % 1 s 1 s -100 % -100 %	500 % 9999 s 2500 s +100 % +100 %	xp referred to measuring range Function off = 0 s Function off = 0 s

Feed forward control

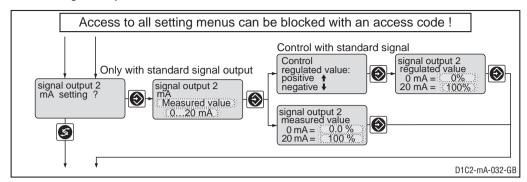


	Initial value	Increment	Lower value	Upper value	Remarks
Feed forward control (Flow)	as per identity code Standard signal 4–20 mA	None 10 Hz 500 Hz 020 mA 420 mA			Signal processing: Signal <0.02 Hz = No flow Signal <0.2 Hz = No flow Signal <0.2 Hz = No flow Signal <0.2 mA = No flow Signal <4.2 mA = No flow
Feed forward control rated value	10 Hz 500 Hz 20 mA	0.01 Hz 1 Hz 0.1 mA	0.1 Hz 5 Hz 0.4 mA	10 Hz 500 Hz 20 mA	Depended on signal type. Maximum limitation of range used.
Feed forward control	multiplicative	multiplicative			
Feed forward control effect		additive			
Feed forward control add. regulated value	100 %	1 %	-500%	+500%	only with add. feed forward control

Standard Signal Output 1

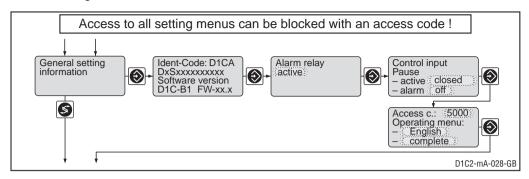


Standard Signal Output 2



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Variable allocation	as per identity code	Measured value Controlled variable			If control applicable
Output range	020 mA	020 mA 420 mA			
Range measured	0–100 % 0–20.00 mA	0,1 % 0,01 mA	−5 % −1,00 mA	105 % 21,00 mA	Minimum range 1 % of measured value
Range controlled variable	0 %+100 %	1 %	–100 %	+100 %	Minimum range 1 %

General Setting



		Possible values			
	Initial value	Increment	Lower value	Upper value	Remarks
Alarm relay	active	active not active			
Pause	Pause	Pause Pause/Hold*			*If Pause/Hold is active, the last valid regulated output signal (PI-part) is hold
Control input pause	closed	closed open			
Alarm Pause	off	off on			Alarm relay can be triggered by pause contact
Access code	5000	1	1	9999	
Language	as per identity code	as per identity code			
Operating menu	complete	restricted complete			

9 Troubleshooting

* at software version 4.63

During Position Upper I Lower	Stop button		Pause	Operation
During servomotor setting Position feed back wrong Upper position <40 % max. value Lower position >30 % range	utton		Pause contact	ion
Direction check Final value small Final value big	Stop	Pause/Hold	Pause	Note text
	Ж О	603)	Symbol
	€ O Stop		Stop	Effect on metering on control
	Stop	PI-part frozen	Stop	ect on control
	No		No	Alarm with acknowledgement
Without correct adjustment the last valid values are still used	Relay drops out	fault check	No firstbox	Remarks
Without correct Adjustment the last valid values are still used of the servomotor correctly	ı		ı	Remedy

Fault	Fault text	Symbol	Effect on metering on control		Alarm with acknowledgement	Remarks	Remedy
Measured value Checkout time measured value exceeded	Check probe	Μ	Basic load	Stop	Yes	Function defeatable	Check function of probe
Signal exceeded/drops below value	Check input	3	Basic load	Stop	Yes	Signal <3.0 \pm 0.2 mA or >23 \pm 0.2 mA	Check probe, transducer and cable connection
Feed forward control Signal exceeded/drops below value	Check feed forward input	Μ			Yes	Signal <3.0 ±0.2 mA or >23 ±0.2 mA Value last valid is used	Check probe, transducer and cable connection
Limit transgression after checkout time limits	Limit 1 ♣◆ Limit 2 ♣◆	Μ	Basic load*	Stop*	Yes	Function defeatable	Define cause, reset values if necessary
Servomotor Position not reached	Servomotor defective	3			Yes	Servomotor closes	Check servomotor
Electronics error	System error EO	03	Stop	Stop	Yes	Elektronic data defective	Call in service